

國立臺灣大學 行為與社會科學研究倫理委員會

Research Ethics Committee
National Taiwan University
No. 1, Sec. 4, Roosevelt Rd., Taipei, Taiwan 10617, R.O.C
Phone: 3366-9956 Fax: 2362-9082

持續審查 審查核可證明

核可日期(持續審查): 2020年5月11日

倫委會案號: 201510EM011

核可證明有效期限: 2020年5月11日起至2021年5月10日

計畫名稱: NDT 中風步態與步態矯正訓練之研究

校/院/系/計畫主持人: 國立陽明大學/生物醫學暨工程學院/物理治療暨輔助科技學系/游忠煌 副教授

計畫文件版本日期: 【研究計畫書, 2018年1月24日】、【知情同意書, 2018年1月24日】

上述計畫業經2020年5月11日國立臺灣大學行為與社會科學研究倫理委員會同意, 符合研究倫理規範。本委員會的運作符合本校行為與社會科學研究倫理準則與規範及政府相關法律規章。

本案需經研究經費補助單位核准同意後, 該計畫始得執行。

計畫主持人最遲應於本核可證明到期前的6週, 提出持續審查申請表, 本案需經持續審查, 方可繼續執行。在計畫執行期間, 若有計畫變更或嚴重不良反應事件, 計畫主持人須依國內及本校相關法令規定通報本委員會。

行為與社會科學研究倫理委員會主任委員 謝世忠



Ethical Review Approval National Taiwan University

Date of approval (Continuing Review): May 11, 2020

NTU-REC No.: 201510EM011

Validity of this approval: from May 11, 2020 to May 10, 2021

Title of protocol: Research on a Gait System for Neuro-Developmental Treatment of Stroke

University/ College/ Department/ Principal Investigator: National Yang-Ming University / School of Biomedical Science and Engineering / Department of Physical Therapy and Assistive Technology / Associate Professor Chung-huang Yu

Version date of documents: 【Research Protocol, January 24, 2018】 , 【Informed Consent Form, January 24, 2018】

The protocol has been approved by Research Ethics Committee of National Taiwan University and has been classified as expedited on May 11, 2020. The committee is organized under, and operates in accordance with, Social and Behavioral Research Ethical Principles and Regulations of National Taiwan University and governmental laws and regulations.

Approval by funding agency is mandatory before project implementation.

Continuing Review Application should be submitted to Research Ethics Committee no later than six weeks before current approval expired. The investigator is required to report protocol amendment and Serious Adverse Events in accordance with the National Taiwan University and governmental laws and regulations.

Chairperson Shih-chung Hsieh
Research Ethics Committee

